

O. Talagrand (LMD)

Objective validation and
evaluation of data
assimilation

Purpose of assimilation

Use all available information in order to determine as accurately as possible the state of the atmospheric or oceanic flow.

Available information consists of

- Observations proper, highly variable in nature, spatial and temporal distribution and accuracy.
- Physical laws governing the flow, available in practice ⁱⁿ ~~under~~ the form of a numerical dynamical model.
- Statistical or asymptotic properties of the flow (ex: existence of approximate geostrophic balance)

$$\begin{cases} Z_1 = x + \xi_1 \\ Z_2 = x + \xi_2 \end{cases}$$

$$\xi_1 = \mathcal{N}(0, \sigma_1^2) \quad \sim \exp\left(-\frac{1}{2} \frac{\xi_1^2}{\sigma_1^2}\right)$$

$$\xi_2 = \mathcal{N}(0, \sigma_2^2) \quad \sim \exp\left(-\frac{1}{2} \frac{\xi_2^2}{\sigma_2^2}\right)$$

Mutually independent!

Probability that

$$x = \xi ?$$

$$x = \xi \iff \xi_1 = z_1 - \xi \text{ and } \xi_2 = z_2 - \xi$$

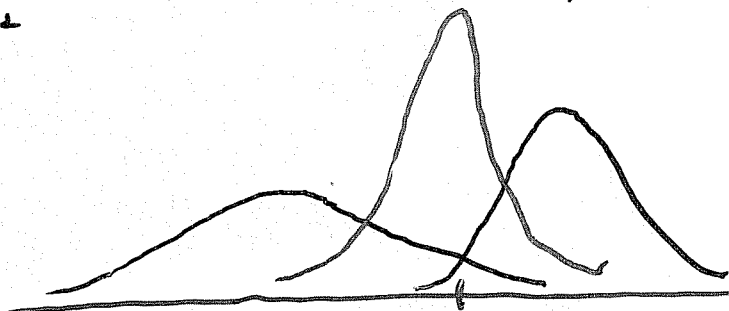
$$P(x = \xi | z_1, z_2) \sim \exp\left[-\frac{1}{2} \frac{(z_1 - \xi)^2}{\sigma_1^2}\right] \exp\left[-\frac{1}{2} \frac{(z_2 - \xi)^2}{\sigma_2^2}\right]$$

$$\sim \exp\left[-\frac{1}{2} \frac{(\xi - x^a)^2}{\sigma^2}\right]$$

$$P(x = \xi | z_1, z_2) = \mathcal{N}(x^a, \sigma^2)$$

$$\begin{cases} x^a = \sigma^2 \left[\frac{z_1}{\sigma_1^2} + \frac{z_2}{\sigma_2^2} \right] \\ \frac{1}{\sigma^2} = \frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2} \end{cases}$$

$$\sigma^2 < (\sigma_1^2, \sigma_2^2)$$



State vector x , belonging to state space \mathcal{S} ($\dim \mathcal{S} = n$), to be estimated.

Data vector z , belonging to data space \mathcal{D} ($\dim \mathcal{D} = m$), available.

$$F(z, x, \zeta) = 0 \quad (1)$$

where ζ is a random element representing the uncertainty on the data (or, more precisely, on the link between the data and the unknown state vector).

For example

$$z = \Gamma x + \zeta$$

Bayesian estimation

Probability that $x = \xi$ for given z ?

$$x = \xi \Leftrightarrow F(z, \xi, \zeta) = 0$$

$$P(x = \xi | z) = P[F(z, \xi, \zeta) = 0] / \int_{\xi} P[F(z, \xi', \zeta) = 0]$$

Unambiguously defined iff, for any z , there is at most one x such that (1) is verified.

\Leftrightarrow data contain information, either directly or indirectly, on any component of x . *Determinacy condition.*

$$\begin{aligned} & P(x=z) \\ &= \frac{P(x \text{ and } z)}{P(z)} \end{aligned}$$

More generally

$$z = f(\mathbf{x}, \zeta)$$

where ζ is 'error' with known pdf. Then

$$P(\mathbf{x}=\xi | z) = \int P[\zeta \text{ such that } f(\xi, \zeta) = z]$$

Makes sense only if, for any ζ , there is at most one ξ such that $f(\xi, \zeta) = z$
(*determinacy* condition)

! Bayesian estimation impossible in practice because

- large numerical dimensions (10^7)
- data error statistics are poorly known (if at all ; model errors).

Need for drastically reduced order description of conditional pdf. Two possibilities

- some estimate of $E(\mathbf{x} | z)$ and reduced order estimate of $E(\mathbf{x}\mathbf{x}^T | z)$
- conditional pdf described by finite ensemble (size up to a few 10^2) ;

$$z = \Gamma x + \zeta$$

Γ known ($m \times n$)-matrix, ζ unknown 'error'

Look for estimated state vector x^a of the form

$$x^a = \alpha + Az$$

subject to

- 1 invariance in change of origin in state space

$$\Rightarrow A\Gamma = I_m$$

- 2 $E[(x_i^a - x_i)^2]$ minimum for any component x_i .

$$x^a = (\Gamma^T S^{-1} \Gamma)^{-1} \Gamma^T S^{-1} [z - \mu]$$

$$P^a \equiv E[(x^a - x)(x^a - x)^T] = (\Gamma^T S^{-1} \Gamma)^{-1}$$

where $\mu = E(\zeta)$ (expectation) and $S = E\{[\zeta - \mu][\zeta - \mu]^T\}$ (covariance matrix)

Best Linear Unbiased Estimator (BLUE) of x from z .

Requires (at least apparently) *a priori* explicit knowledge of first- and second-order statistical moments of error ζ .

Determinacy condition $\Leftrightarrow \text{rank} \Gamma = n. \quad \Rightarrow m \geq n$

In case ζ is gaussian, $\zeta = \mathcal{N}[\mu, S]$, BLUE achieves bayesian estimation in the sense that

$$P(x | z) = \mathcal{N}[x^a, P^a]$$

Variational form.

BLUE x^a minimizes following scalar *objective function*, defined on state space \mathcal{S}

$$\mathcal{J}(\xi) \equiv (1/2) [\Gamma\xi - (z-\mu)]^T S^{-1} [\Gamma\xi - (z-\mu)]$$

BLUE is invariant in any invertible linear change of coordinates, either in state or data space.

From now on, unless specified otherwise, data assumed to be unbiased ($\mu = 0$).

If determinacy condition is verified, it is always possible to decompose data into

A '*background*' estimate (*e. g.* forecast from the past), belonging to *state space*, with dimension n

$$x^b = x + \zeta^b$$

An additional set of data (*e. g.* observations), belonging to *observation space*, with dimension $m - n = p$

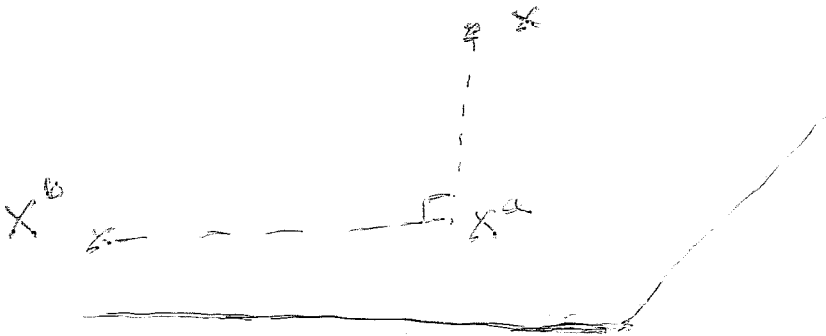
$$y = Hx + \varepsilon$$

Least error variance estimate - BLUE

$$x^a = x^b + P^b H^T (HP^b H^T + R)^{-1} (y - Hx^b) \quad (1)$$

with $P^b \equiv E(\zeta^b \zeta^{bT})$ (also often denoted B), $R \equiv E(\varepsilon \varepsilon^T)$
 $E(\varepsilon \zeta^{bT}) = 0$ (not restrictive)

$$P^a \equiv E[(x - x^a)(x - x^a)^T] = P^b - P^b H^T (HP^b H^T + R)^{-1} HP^b$$



$d \equiv y - Hx^b$ is the *innovation vector*

(1) means that the increment $x^a - x^b$ is the orthogonal projection, in the sense of statistical covariance, of the background error $x - x^b$ onto the space spanned by the innovation vector. As a consequence, the estimation error $x^a - x$ is uncorrelated with the innovation vector, *i. e.*

$$E[(x^a - x) d^T] = 0$$

Variational formulation

Analysis x^a minimizes *objective function* defined on state space

$\xi \rightarrow$

$$J(\xi) \equiv (1/2) (\xi - x^b)^T [P^b]^{-1} (\xi - x^b) + (1/2) (H\xi - y)^T R^{-1} (H\xi - y)$$

Determination of the BLUE requires (at least apparently) the a priori specification of the first- and second-order statistical moments of the errors affecting the data

(general bayesian estimation requires the specification of the entire probability distribution of the errors)

Questions

- Is it possible to objectively evaluate the quality of an assimilation system ?

- Is it possible to objectively evaluate the first- and second-order statistical moments of the data errors, whose specification is (at least apparently) required for determining the *BLUE* ?

- Is it possible to objectively determine if an assimilation system is optimal ?

- More generally, how to make the best of an assimilation system ?

and

- Is assimilation worth all the concern we give to it ?

$$\begin{cases} x^b = x + \zeta^b \\ d \equiv y - Hx^b = \varepsilon - H\zeta^b \end{cases}$$

Innovation vector is the only objective source of information on data error. Implementing assimilation requires knowing, at least to some extent, how the background on the one hand, the observations on the other, contribute to the innovation. That cannot be obtained from the innovation alone.

We will consider assimilation schemes of the form

$$x^a = x^b + K d \tag{2}$$

where K is the *gain matrix* (not necessarily optimal).

(2) \Leftrightarrow if data are exact, then analysis is exact too ($x^a = x$).

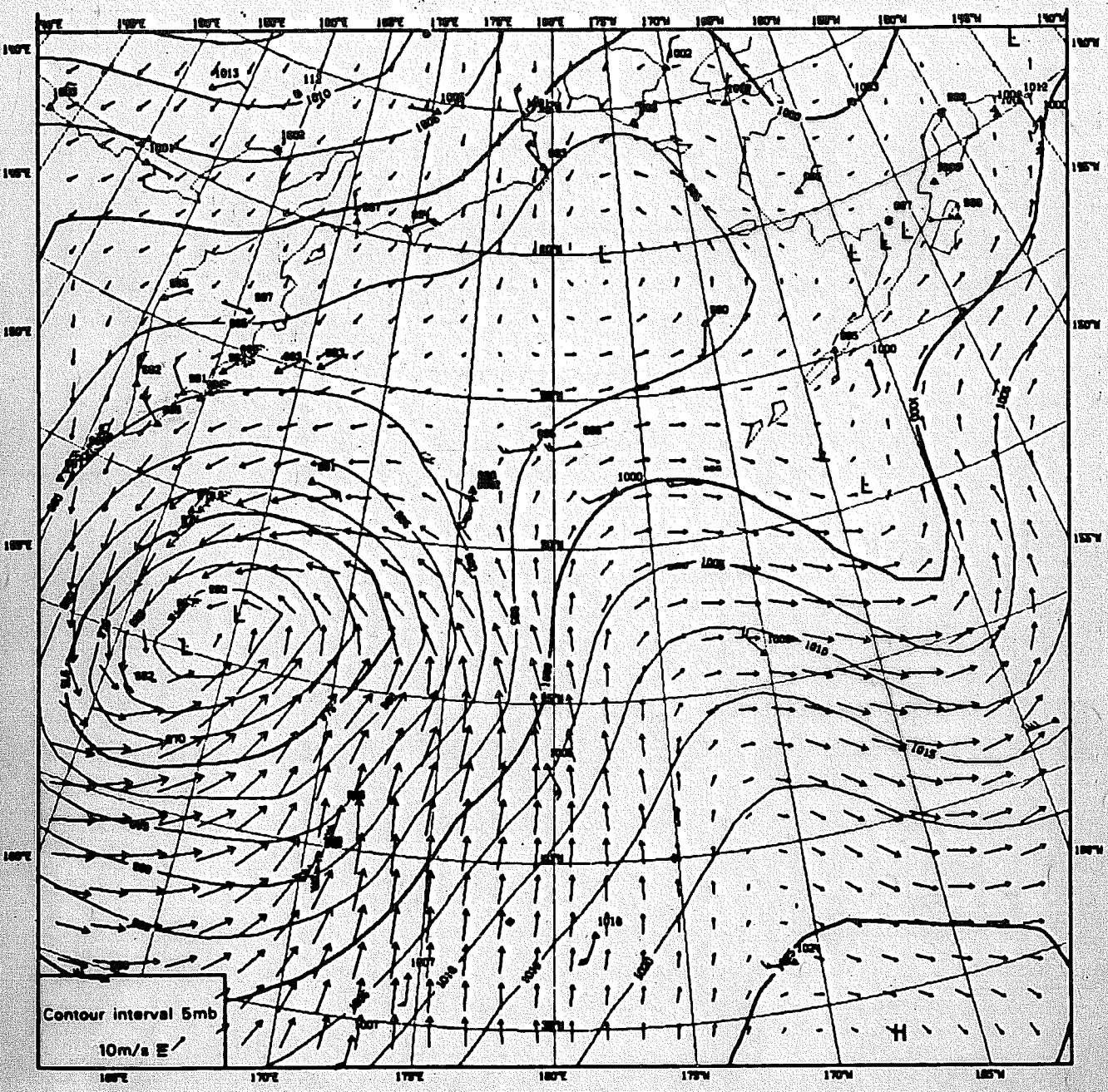


Fig. 4 Sea level pressure and wind forecast corresponding to the central area of Fig. 1, with plotted surface observations of pressure and wind (each fleche = 5 m/s).

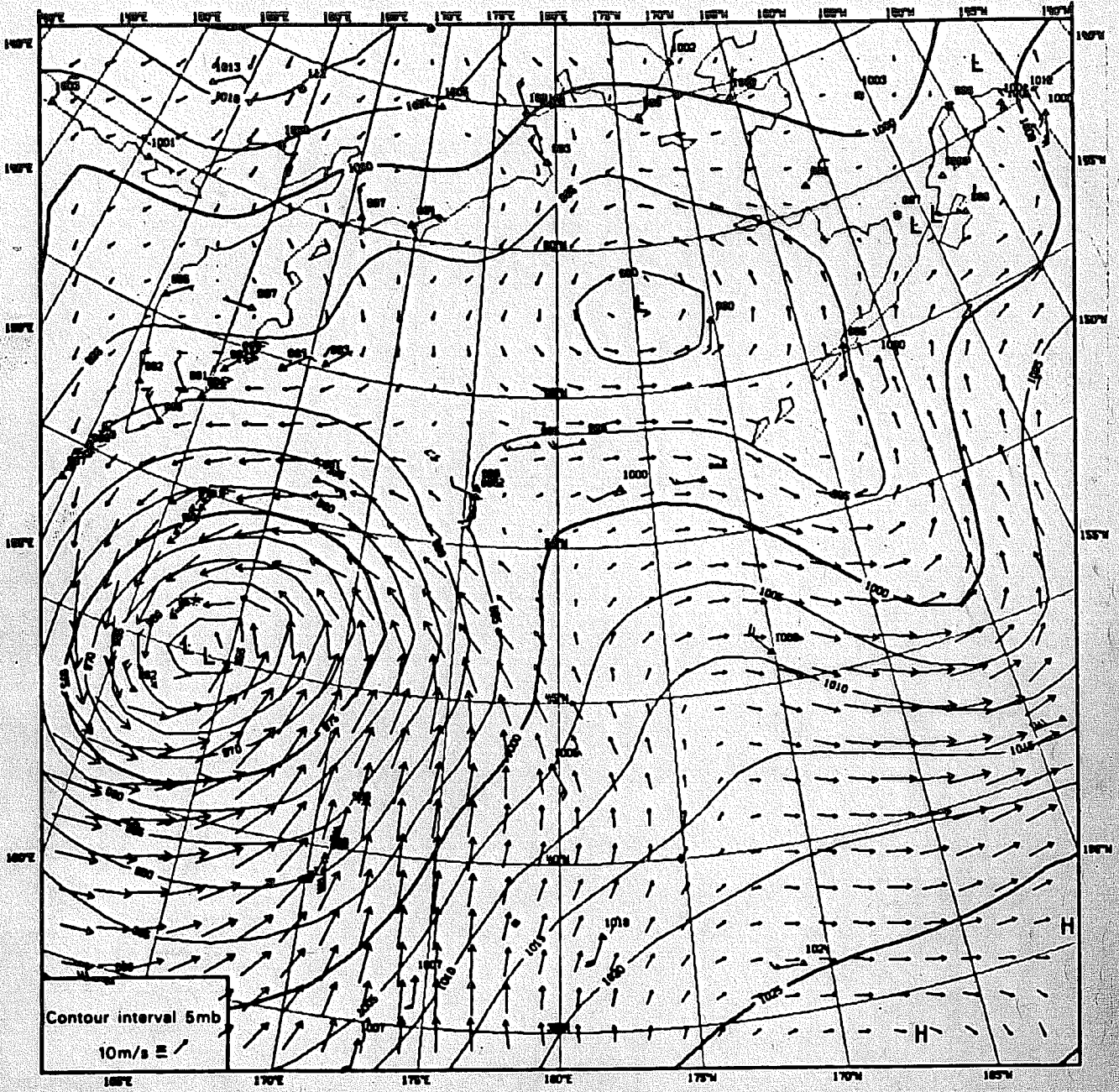


Fig. 5 As Fig. 4 for the analysis in the data assimilation cycle

Difference between data and assimilated fields

$$\delta \equiv \begin{pmatrix} x^b - x^a \\ y - Hx^a \end{pmatrix} = z - \Gamma x^a$$

$$\delta = \begin{pmatrix} -Kd \\ (I_p - HK)d \end{pmatrix}$$

For given gain matrix K , one-to-one transformation between d and δ . Exactly equivalent to perform diagnostics on either innovation or *data-minus-analysis (DmA)* difference.

Objective validation of quality of ^{an} assimilation system can be made only by comparison with unbiased independent data, i.e. data affected by errors which are statistically independent of errors affecting the data used in the assimilation.

Innovation vector $d = y - Hx^b$ is only source of objective information.

Magnitude: measure of quality of assimilation

~~Like~~ Other diagnostic. Check if statistics of innovation vector are consistent with a priori hypotheses

$$E(d) = 0$$

$$E(dd^T) = H P^b H^T + R$$

[Check if d is Gaussian]

if consistency

$$E(S) = 0$$

Any systematic bias in S is the signature of an improperly taken into account bias in the data

$$E(S S^T) = S - \underbrace{\Gamma (\Gamma^T S^{-1} \Gamma)^{-1} \Gamma^T}_{> 0} = S - \Gamma \rho \Gamma^T$$

Assimilated fields must fit data to within assumed accuracy of the latter. (system is 'efficient', as defined by Hollingsworth and Lönnberg, 1989)

(if they do not, inconsistency between a priori assumed statistics on S and real statistics.

NCMRWF (K. Bhattacharya)

NORTHERN HEMISPHERE (O-A) RMS/OBS.ERR SSI - JAN 2002

LEVEL (hPa)	RADIOSONDE TD	RAWINSONDE UW	RAWINSONDE VW
50.	1.3	1.4	1.0
70.	0.9	1.1	0.9
100.	0.8	1.0	1.0
150.	0.8	0.9	0.9
200.	0.8	0.8	0.8
250.	0.8	0.8	0.8
300.	0.8	0.8	0.8
400.	0.8	0.8	0.9
500.	0.7	0.9	0.9
700.	0.7	0.9	0.8
850.	0.9	0.9	0.9
1000.	1.3	0.9	0.9

NCMR WF (K. Bhattacharya)

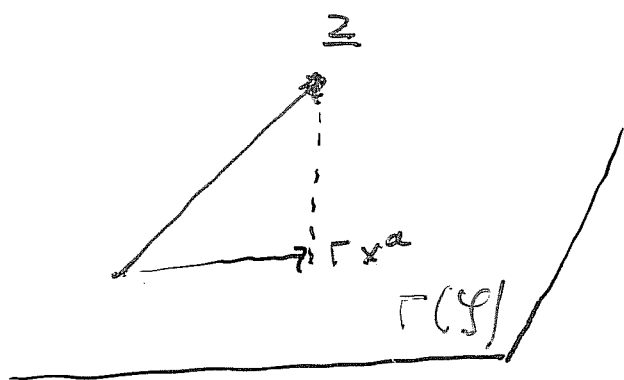
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300.	0.6	0.6	0.7
400.	0.6	0.6	0.6
500.	0.7	0.7	0.7
700.	0.8	0.8	0.8
850.	1.1	0.8	0.8
1000.	1.4	0.8	0.8

$$J(\underline{z}) = \frac{1}{2} (\Gamma \underline{z} - \underline{z})^T S^{-1} (\Gamma \underline{z} - \underline{z})$$

$$\langle \underline{z}, \underline{z}' \rangle = \underline{z}^T S^{-1} \underline{z}' \quad \text{is a (proper)}$$

scalar product in
data space \mathcal{D} (Mahalanobis)



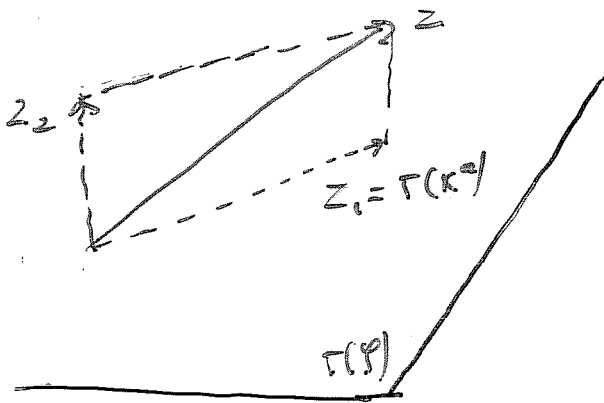
Computing the BLUE amounts to

- Projecting data vector \underline{z} onto image space $\Gamma(Y)$ according to the Mahalanobis scalar product

- Taking the inverse of the projection through Γ (unambiguously defined if null space of Γ is void)

The PCA difference $z - \Gamma x^a$ is the component of the data vector that is discarded in analysis.

Decompose data space \mathcal{D} into image space $\Gamma(\mathcal{S})$ and space orthogonal to $\Gamma(\mathcal{S})$ wrt to S -Mahalanobis scalar product.



$$\Gamma = \begin{pmatrix} \Gamma_1 \\ 0 \end{pmatrix}$$

$$z = \begin{pmatrix} z_1 = \Gamma_1 x + \xi_1 \\ z_2 = \xi_2 \end{pmatrix}$$

$$S = \begin{pmatrix} \xi_1 & 0 \\ 0 & \xi_2 \end{pmatrix}$$

$$\begin{cases} x^a = (\Gamma_1^T \xi_1^{-1} \Gamma_1)^{-1} \Gamma_1^T \xi_1^{-1} z_1 = \Gamma_1^{-1} z_1 \\ p^a = (\Gamma_1^T \xi_1^{-1} \Gamma_1)^{-1} \end{cases}$$

in A-difference

$$z = \Gamma x^a$$

$$s = z - \Gamma x^a = \begin{pmatrix} z_1 - \Gamma_1 x^a = 0 \\ z_2 = \xi_2 \end{pmatrix}$$

$$E(s) = E(\xi_2)$$

$$E(s's^T) = E(\xi_2 \xi_2^T)$$

Inconsistency iff $E(\xi_2) \neq 0$ and/or $E(\xi_2 \xi_2^T) \neq 0$

So what?

$$\begin{cases} z_1 = x + \xi_1 \\ z_2 = x + \xi_2 \end{cases} \quad \begin{array}{l} n=1 \\ m=2 \end{array}$$

We do the analysis under the assumption

that

$$E(\xi_1) = E(\xi_2) = 0$$

$$E(\xi_1^2) = E(\xi_2^2) = \sigma^2 \quad E(\xi_1 \xi_2) = 0$$

$$\implies x^a = \frac{1}{2}(z_1 + z_2) \quad E[(x^a - x)^2] = \frac{\sigma^2}{2}$$

Innovation $d = z_1 - z_2$

We expect $E(d) = 0 \quad E(d d^T) = 2\sigma^2$

We observe $E(d) = 2b \quad E(d d^T) = 4b^2 + 2\Delta^2$

Inconsistent iff $b \neq 0$ and/or $\Delta^2 \neq \sigma^2$

$$E(d) = 2\theta$$

(A)

$$E(d^2) = 4\theta^2 + 2\Delta^2$$

$$\text{IE } E(\xi_1) = -E(\xi_2) = \theta$$

$$E[(\xi_1 - \theta)^2] = E[(\xi_2 + \theta)^2] = \sigma^2$$

$$E[(\xi_1 - \theta)(\xi_2 + \theta)] = c\sigma^2$$

with
$$\sigma^2 = \frac{\sigma^2 + \Delta^2}{2}$$

$$c = \frac{\sigma^2 - \Delta^2}{\sigma^2 + \Delta^2}$$

The quantities x^a and $E[(x^a - x)^2]$ are unchanged, while consistency with

(A) is achieved.

In the above example, if it is

known that $E(\xi_1 \xi_2) = 0$, then

necessarily the weights given to

z_1 and z_2 are > 0 , and

$$E[(x^a - \kappa)^2] < d E(d^2)$$

$$E[(x^a - \kappa)^2] < E(d^2)$$

~~2 parameters ($E(\xi_1)$ and $E(\xi_2)$) for are available for~~

If either $E(\xi_1)$ or $E(\xi_2)$ is known, then the knowledge of $E(d)$ determines the unknown bias.

Similarly, the knowledge of one or two of the three parameters $E(\xi_1^2)$, $E(\xi_2^2)$ and c determines, together with the knowledge of $E(d^2)$, one or two conditions on the unknown parameters.

In the above example, if it is known, e.g., that $c=0$, one condition is then imposed on the weights given to ξ_1 and ξ_2 , and on the analysis error. If we want for instance to keep the weights equal, then necessarily $E[(x^a - x)^2] = 0$

A possible inconsistency between expected or observed statistics of δ (or, equivalently, of innovation d) can always be resolved without changing x^a nor p^a .

Consistency between assumed and observed statistics of innovation is not sufficient for ensuring optimality of assimilation. It is not even necessary.

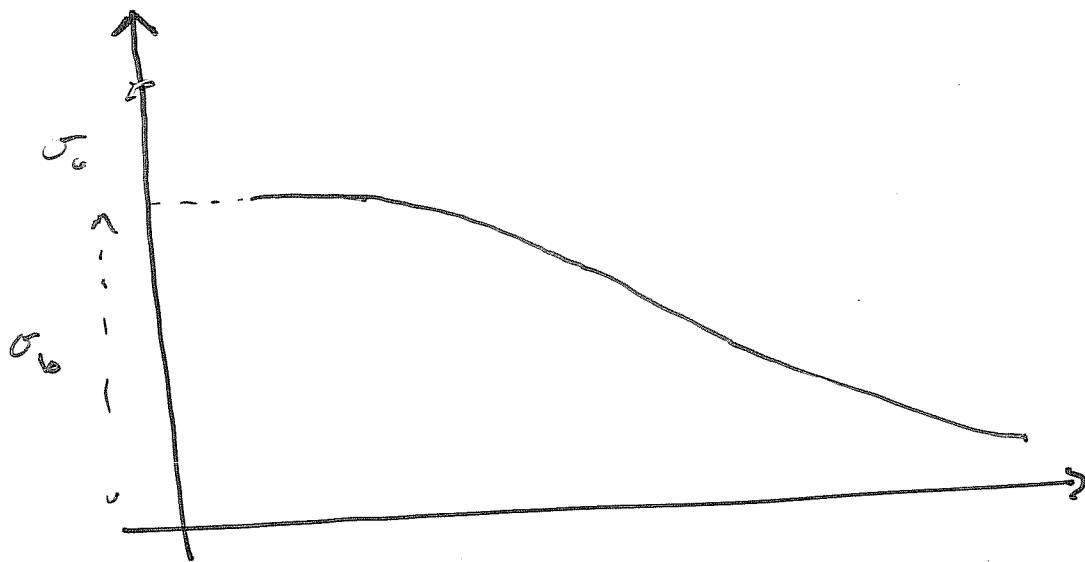
Any inconsistency between the expected and actually observed statistics of the data-minus-analysis difference can always be resolved without modification to the analysis, nor to the associated estimated error.

Independent hypotheses, which cannot be objectively validated (at least on the basis of the data-minus-analysis difference) are necessary.

Problem. Find minimum set of hypotheses, leaving only parameters that can be determined from statistics of the innovation vector.

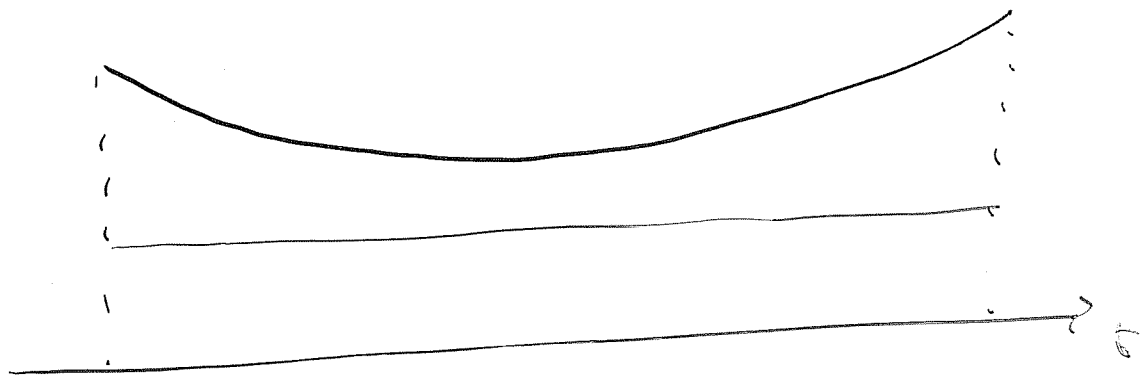
If a priori hypotheses are made, then statistics of the innovation vector (or, equivalently, of the DMA-difference) can be used for determining biases and/or covariances

(R. Daley) Assume observation errors are mutually uncorrelated and uncorrelated with background errors.



Then spatial covariance of innovation is spatial correlation of ~~innovation~~ background error. Variance of background and observation errors can be evaluated by extrapolation to zero distance

Strong constraint variational assimilation



If observational error known, and uncorrelated with model error, misfit between minimizing solution and observations provides integrated estimate of model error.

(Kalman Filter, ~~Model Error~~ assumed to be uncorrelated in time (necessary for having both sequentiality and optimality) \Rightarrow adaptive filtering (Hoang et al., ...)

Variational assimilation (either 3-D or 4-D)

$$\mathcal{J}(\xi) \equiv (1/2) (\xi - x^b)^T [P^b]^{-1} (\xi - x^b) + (1/2) (H\xi - y)^T R^{-1} (H\xi - y)$$

Minimum reached for $\xi = x^a$. For a perfectly consistent system

$$\mathcal{J}(x^a) = (1/2) d^T [E(dd^T)]^{-1} d$$

Minimum of objective function is norm of innovation with respect to its own Mahalanobis scalar product. On expectation

$$E[\mathcal{J}(x^a)] = p/2$$

Often called χ^2 -criterion.

3.1.2 Numerical results

The main result is that the two algorithms converge to the true state with identical cost and accuracy. This first experiment show that the practical efficiency of DA in comparison with the usual 4D-Var.

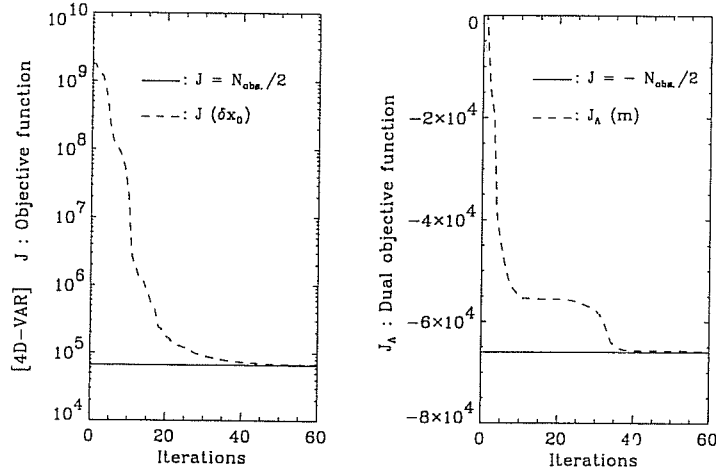
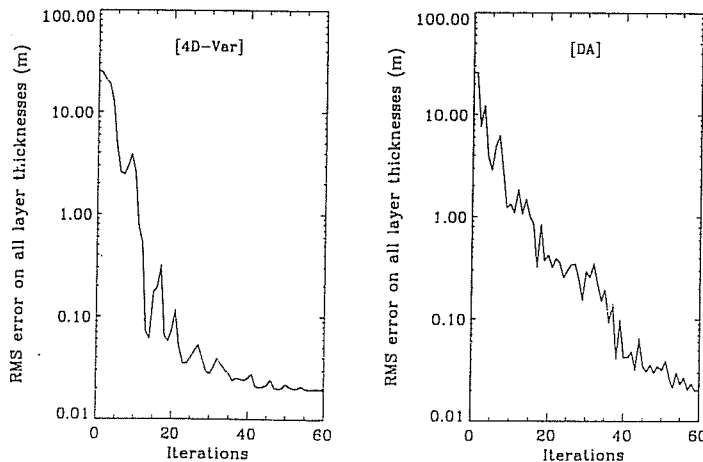


FIG. 2 - Objective functions

FIG. 2 gives proof of the property (19) and compare the minimal numerical values of J and J_A to the statistical expectation: $J_{\text{stat}} = N_{\text{obs}}/2$ with $N_{\text{obs}}=N_{\text{state}}$. Note that the null initial value of the dual cost function (12) is explained by the use of a null increment at the beginning of the minimization. The decrease of the two objective function is not identical but the primal and the dual algorithms need the same number of iterations. From this experiment, we can assess the equivalence between both methods in term of numerical results at the end of the minimizations.

FIG. 3 - RMS error at the time t_n

Annularis eferal

number of eferal lines

0,45

0,41

0,43

0,41

0,38

0,37

0,38

0,36

0,36

0,35

0,36

0,34

0,36

0,36

0,37

0,35

0,36

0,36

0,37

0,36

0,40

/scratch/rd/daa/ebmg/logdir/20030101/main/00/an/4dvar/uptraj_1/ifsmin.1 :					
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GREPCOST - ITER, SIM, JO, JB, JC	999 999	583351.330251	60681.8576886		
20					
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Jo Global :	1391118	512489.3745112	57412.3877855	0.37	5234.061281
GREPCOST - ITER, SIM, JO, JB, JC	999 999	512489.374511	57412.3877855		
56					
/scratch/rd/daa/ebmg/logdir/20030102/main/00/an/4dvar/uptraj_1/ifsmin.1 :					
Jo Global :	1460413	560044.4343723	56877.7970359	0.38	5475.952246
GREPCOST - ITER, SIM, JO, JB, JC	999 999	560044.434372	56877.7970359		
10					
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Jo Global :	1371637	502648.7127915	53200.0343999	0.37	4499.520897
GREPCOST - ITER, SIM, JO, JB, JC	999 999	502648.712792	53200.0343999		
98					
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Jo Global :	1439923	527864.7124925	56371.5869005	0.37	4108.714252
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74					
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55					
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Jo Global :	1391729	483022.4228964	51947.4256765	0.35	3735.044590
GREPCOST - ITER, SIM, JO, JB, JC	999 999	483022.422896	51947.4256765		
37					
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Jo Global :	1425827	516035.2023126	53171.8232700	0.36	3867.648157
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81					
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Jo Global :	1500738	554292.5152698	56842.3382909	0.37	4313.191710
GREPCOST - ITER, SIM, JO, JB, JC	999 999	554292.515270	56842.3382909		
19					
/scratch/rd/daa/ebmg/logdir/20030108/main/12/an/4dvar/uptraj_1/ifsmin.1 :					
Jo Global :	1478979	519652.0339623	54815.3317792	0.35	4088.292663
GREPCOST - ITER, SIM, JO, JB, JC	999 999	519652.033962	54815.3317792		
85					
/scratch/rd/daa/ebmg/logdir/20030109/main/00/an/4dvar/uptraj_1/ifsmin.1 :					
Jo Global :	1501182	536600.4381115	55189.8771365	0.36	3954.585491
GREPCOST - ITER, SIM, JO, JB, JC	999 999	536600.438111	55189.8771365		
99					
/scratch/rd/daa/ebmg/logdir/20030109/main/12/an/4dvar/uptraj_1/ifsmin.1 :					
Jo Global :	1458405	521047.2001178	54325.4354694	0.36	3858.839886
GREPCOST - ITER, SIM, JO, JB, JC	999 999	521047.200118	54325.4354694		
32					
/scratch/rd/daa/ebmg/logdir/20030110/main/00/an/4dvar/uptraj_1/ifsmin.1 :					
Jo Global :	1479196	551524.9346666	54935.2610658	0.37	3966.946995
GREPCOST - ITER, SIM, JO, JB, JC	999 999	551524.934667	54935.2610658		
98					
/scratch/rd/daa/ebmg/logdir/20030110/main/12/an/4dvar/uptraj_1/ifsmin.1 :					
Jo Global :	1442781	519009.2804139	54424.8595290	0.36	3934.851931
GREPCOST - ITER, SIM, JO, JB, JC	999 999	519009.280414	54424.8595290		
09					
/scratch/rd/daa/ebmg/logdir/20030111/main/00/an/4dvar/uptraj_1/ifsmin.1 :					
Jo Global :	1498818	545469.1467534		0.36	

GREPCOST - ITER, SIM, JO, JB, JC	999 999	545469.146753	54571.9950191	3864.932864
00				
/scratch/rd/daa/ebmg/logdir/20030111/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1404038	499560.3144969	0.36	0.40
GREPCOST - ITER, SIM, JO, JB, JC	999 999	499560.314497	52394.3272952	3765.473571
79				
/scratch/rd/daa/ebmg/logdir/20030112/main/00/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1452999	531075.9594903	0.37	0.41
GREPCOST - ITER, SIM, JO, JB, JC	999 999	531075.959490	55941.5710915	4177.026832
15				
/scratch/rd/daa/ebmg/logdir/20030112/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1357049	484944.1940747	0.36	0.40
GREPCOST - ITER, SIM, JO, JB, JC	999 999	484944.194075	52517.7255095	3736.706266
78				
/scratch/rd/daa/ebmg/logdir/20030113/main/00/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1337228	536122.2229325	0.40	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	536122.222933	53429.8153097	4053.930255
99				
/scratch/rd/daa/ebmg/logdir/20030113/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1311265	478570.4071103	0.36	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	478570.407110	52561.1547953	3904.290460
13				
/scratch/rd/daa/ebmg/logdir/20030114/main/00/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1453254	567289.3811072	0.39	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	567289.381107	57475.6966038	4801.895527
70				
/scratch/rd/daa/ebmg/logdir/20030114/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1467896	548622.2342518	0.37	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	548622.234252	56298.4672026	4302.401824
15				
/scratch/rd/daa/ebmg/logdir/20030115/main/00/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1494508	555721.3641453	0.37	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	555721.364145	57345.3948895	4285.092207
98				
/scratch/rd/daa/ebmg/logdir/20030115/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1318768	492015.2817690	0.37	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	492015.281769	53657.0226403	3725.264802
29				
/scratch/rd/daa/ebmg/logdir/20030116/main/00/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1202340	502028.6625365	0.42	0.46
GREPCOST - ITER, SIM, JO, JB, JC	999 999	502028.662537	51815.0327751	4201.291031
35				
/scratch/rd/daa/ebmg/logdir/20030116/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1489159	556783.2050098	0.37	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	556783.205010	58472.8524180	4362.181995
21				
/scratch/rd/daa/ebmg/logdir/20030117/main/00/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1495427	568478.7591876	0.38	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	568478.759188	57318.6283788	4513.011533
37				
/scratch/rd/daa/ebmg/logdir/20030117/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1494243	544629.9026914	0.36	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	544629.902691	56138.0457273	4327.980181
86				
/scratch/rd/daa/ebmg/logdir/20030118/main/00/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1430028	540130.5317339	0.38	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	540130.531734	54712.0229546	4332.500891
95				
/scratch/rd/daa/ebmg/logdir/20030118/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1437608	508122.5669298	0.35	
GREPCOST - ITER, SIM, JO, JB, JC	999 999	508122.566930	53846.3157778	4024.626659
81				
/scratch/rd/daa/ebmg/logdir/20030119/main/00/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1507042	543897.2238212	0.36	0.40
GREPCOST - ITER, SIM, JO, JB, JC	999 999	543897.223821	54585.7094448	4323.183151
20				
/scratch/rd/daa/ebmg/logdir/20030119/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1352213	485534.4666308	0.36	0.40
GREPCOST - ITER, SIM, JO, JB, JC	999 999	485534.466631	52123.2692774	3939.344145
35				
/scratch/rd/daa/ebmg/logdir/20030120/main/00/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1484311	546480.3748742	0.37	0.41
GREPCOST - ITER, SIM, JO, JB, JC	999 999	546480.374874	54694.5721515	4597.361035
02				
/scratch/rd/daa/ebmg/logdir/20030120/main/12/an/4dvar/uptraj_1/ifsmin.1 :				
Jo Global :	1413737	502382.8863849	0.36	0.40
GREPCOST - ITER, SIM, JO, JB, JC	999 999	502382.886385	53745.6509243	4302.119900
92				

A modification will be made to the following satellite files (G. Kelly)

94	/scratch/rd/daa/ebjb/logdir/20030101/main/00/an/4dvar/uptraj_1/ifsmin.1 :								1,27
	Jo Global :	278737	316472.3489264	1.14					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		316472.348926	34546.5870829				3864.615055	
09	/scratch/rd/daa/ebjb/logdir/20030101/main/12/an/4dvar/uptraj_1/ifsmin.1 :								1,34
	Jo Global :	209335	245958.3558854	1.17					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		245958.355885	31350.0436678				3283.661589	
33	/scratch/rd/daa/ebjb/logdir/20030102/main/00/an/4dvar/uptraj_1/ifsmin.1 :								1,24
	Jo Global :	270689	293848.3429347	1.09					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		293848.342935	33005.2540858				3137.783602	
30	/scratch/rd/daa/ebjb/logdir/20030102/main/12/an/4dvar/uptraj_1/ifsmin.1 :								1,25
	Jo Global :	227041	247046.3459600	1.09					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		247046.345960	29456.7105689				2751.488523	
24	/scratch/rd/daa/ebjb/logdir/20030103/main/00/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	290767	288908.0527105	0.99					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		288908.052711	32236.7113220				2520.907887	
77	/scratch/rd/daa/ebjb/logdir/20030103/main/12/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	256155	258081.0190496	1.01					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		258081.019050	31782.0545481				2418.500437	
73	/scratch/rd/daa/ebjb/logdir/20030104/main/00/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	295499	292890.0818218	0.99					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		292890.081822	32810.1438231				2503.573236	
17	/scratch/rd/daa/ebjb/logdir/20030104/main/12/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	240572	238527.4531333	0.99					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		238527.453133	30347.0163316				2138.047378	
60	/scratch/rd/daa/ebjb/logdir/20030105/main/00/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	281473	264091.2223258	0.94					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		264091.222326	31121.5409696				2409.695978	
76	/scratch/rd/daa/ebjb/logdir/20030105/main/12/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	217305	214307.5882262	0.99					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		214307.588226	28288.2805152				1851.639418	
31	/scratch/rd/daa/ebjb/logdir/20030106/main/00/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	282812	261219.1117783	0.92					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		261219.111778	30740.8703977				2002.492142	
08	/scratch/rd/daa/ebjb/logdir/20030106/main/12/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	202966	196973.5616650	0.97					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		196973.561665	27546.4142755				1647.925735	
06	/scratch/rd/daa/ebjb/logdir/20030107/main/00/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	273642	255595.3144872	0.93					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		255595.314487	30410.5545157				1974.851646	
50	/scratch/rd/daa/ebjb/logdir/20030107/main/12/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	259690	250369.4266358	0.96					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		250369.426636	31351.3484838				1920.428417	
44	/scratch/rd/daa/ebjb/logdir/20030108/main/00/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	298968	281955.6530369	0.94					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		281955.653037	32898.8882291				2246.199661	
59	/scratch/rd/daa/ebjb/logdir/20030108/main/12/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	260220	246674.6748573	0.95					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		246674.674857	30909.5577790				1913.595214	
81	/scratch/rd/daa/ebjb/logdir/20030109/main/00/an/4dvar/uptraj_1/ifsmin.1 :								1,02
	Jo Global :	291484	262459.5897328	0.90					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		262459.589733	31891.9909930				2062.470751	
94	/scratch/rd/daa/ebjb/logdir/20030109/main/12/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	261671	247835.1364361	0.95					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		247835.136436	31778.0656115				1798.778030	
97	/scratch/rd/daa/ebjb/logdir/20030110/main/00/an/4dvar/uptraj_1/ifsmin.1 :								
	Jo Global :	296244	278222.9430185	0.94					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		278222.943018	32205.4800151				2025.182585	
73	/scratch/rd/daa/ebjb/logdir/20030110/main/12/an/4dvar/uptraj_1/ifsmin.1 :								1,04
	Jo Global :	259901	237290.8709594	0.91					
	GREPCOST - ITER, SIM, JO, JB, JC 999 999		237290.870959	30498.7405193				1911.340193	
	/scratch/rd/daa/ebjb/logdir/20030111/main/00/an/4dvar/uptraj_1/ifsmin.1 :								1,02
	Jo Global :	294446	267026.0823887	0.91					

GREPCOST - ITER, SIM, JO, JB, JC	999 999	267026.082389	30723.7970768	1996.283467
52	/scratch/rd/daa/ebjb/logdir/20030111/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	242028	222600.5295437	0.92
GREPCOST - ITER, SIM, JO, JB, JC	999 999	222600.529544	29443.8972806	1916.960673
57	/scratch/rd/daa/ebjb/logdir/20030112/main/00/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	276392	253085.1235589	0.92
GREPCOST - ITER, SIM, JO, JB, JC	999 999	253085.123559	31601.8268183	2047.350471
92	/scratch/rd/daa/ebjb/logdir/20030112/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	211324	209277.4011967	0.99
GREPCOST - ITER, SIM, JO, JB, JC	999 999	209277.401197	29788.2113005	1865.544508
54	/scratch/rd/daa/ebjb/logdir/20030113/main/00/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	280574	285086.4593491	1.02
GREPCOST - ITER, SIM, JO, JB, JC	999 999	285086.459349	31884.1433896	2308.529282
07	/scratch/rd/daa/ebjb/logdir/20030113/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	212120	222359.1023980	1.05
GREPCOST - ITER, SIM, JO, JB, JC	999 999	222359.102398	29635.3546027	2042.579575
63	/scratch/rd/daa/ebjb/logdir/20030114/main/00/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	284699	296239.7581921	1.04
GREPCOST - ITER, SIM, JO, JB, JC	999 999	296239.758192	34376.8393503	2686.776592
59	/scratch/rd/daa/ebjb/logdir/20030114/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	268225	265914.3565779	0.99
GREPCOST - ITER, SIM, JO, JB, JC	999 999	265914.356578	32292.1346056	2074.917494
36	/scratch/rd/daa/ebjb/logdir/20030115/main/00/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	296343	275720.8803268	0.93
GREPCOST - ITER, SIM, JO, JB, JC	999 999	275720.880327	33038.6553805	1973.109366
94	/scratch/rd/daa/ebjb/logdir/20030115/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	265990	244775.3071775	0.92
GREPCOST - ITER, SIM, JO, JB, JC	999 999	244775.307178	31057.1861847	1858.572957
01	/scratch/rd/daa/ebjb/logdir/20030116/main/00/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	304862	291180.1664443	0.96
GREPCOST - ITER, SIM, JO, JB, JC	999 999	291180.166444	32061.5070201	2136.046411
72	/scratch/rd/daa/ebjb/logdir/20030116/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	265534	266608.6332511	1.00
GREPCOST - ITER, SIM, JO, JB, JC	999 999	266608.633251	33235.3025602	2154.727906
36	/scratch/rd/daa/ebjb/logdir/20030117/main/00/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	305053	285672.5238977	0.94
GREPCOST - ITER, SIM, JO, JB, JC	999 999	285672.523898	33427.5615669	2297.013787
68	/scratch/rd/daa/ebjb/logdir/20030117/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	258824	249297.7748541	0.96
GREPCOST - ITER, SIM, JO, JB, JC	999 999	249297.774854	31236.2493768	2050.857644
44	/scratch/rd/daa/ebjb/logdir/20030118/main/00/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	295150	269780.4915688	0.91
GREPCOST - ITER, SIM, JO, JB, JC	999 999	269780.491569	31959.0114224	2222.334260
81	/scratch/rd/daa/ebjb/logdir/20030118/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	238708	225648.9999502	0.95
GREPCOST - ITER, SIM, JO, JB, JC	999 999	225648.999950	31055.8556146	2057.144659
39	/scratch/rd/daa/ebjb/logdir/20030119/main/00/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	280492	259695.4105145	0.93
GREPCOST - ITER, SIM, JO, JB, JC	999 999	259695.410514	30822.5631781	2308.011236
27	/scratch/rd/daa/ebjb/logdir/20030119/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	211307	213670.7624570	1.01
GREPCOST - ITER, SIM, JO, JB, JC	999 999	213670.762457	29205.2420348	1903.644222
99	/scratch/rd/daa/ebjb/logdir/20030120/main/00/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	282709	260686.0339818	0.92
GREPCOST - ITER, SIM, JO, JB, JC	999 999	260686.033982	30471.3185585	2297.012622
19	/scratch/rd/daa/ebjb/logdir/20030120/main/12/an/4dvar/uptraj_1/ifsmin.1	:		
	Jo Global :	210251	215378.5076491	1.02
GREPCOST - ITER, SIM, JO, JB, JC	999 999	215378.507649	30020.5302435	2041.798946
61				

Objective function

$$\mathcal{J}(\xi) = \sum_k \mathcal{J}_k(\xi)$$

where

$$\mathcal{J}_k(\xi) \equiv (1/2) (H_k \xi - y_k)^T S_k^{-1} (H_k \xi - y_k)$$

with $\dim y_k = m_k$

Accuracy of analysis

$$[P^a]^{-1} = \sum_k H_k^T S_k^{-1} H_k$$

$$\begin{aligned} 1 &= (1/n) \sum_k \text{tr}(P^a H_k^T S_k^{-1} H_k) \\ &= (1/n) \sum_k \text{tr}(S_k^{-1/2} H_k P^a H_k^T S_k^{-1/2}) \end{aligned}$$

Measure of the relative contribution of subset of data y_k to overall accuracy of assimilation.

Invariant in linear change of coordinates in data space \Rightarrow valid for *any* subset of data.

Can be numerically computed (Wahba, Fisher, Desroziers and Ivanov).

Can be extended to measure of relative contribution of any subset of data to accuracy of any subset of analysed fields (but practical computation?).

For a perfectly consistent system

$$E[\mathcal{J}_k(x^d)] = (1/2) [m_k - \text{tr}(S_k^{-1/2} H_k P^d H_k^T S_k^{-1/2})]$$

It is possible to compare $E[\mathcal{J}_k(x^d)]$, as determined operationally, and $(1/2) [m_k - \text{tr}(S_k^{-1/2} H_k P^d H_k^T S_k^{-1/2})]$, as computed directly, thus providing a check of the consistency of the assimilation system.

Also, $E[\mathcal{J}_k(x^d)]$ must be less than $m_k/2 \Leftrightarrow$ every piece of data must fit the analysis to within its assumed accuracy.

In particular

- Relative contribution of background

$$(S_k = P^b, H_k = \Sigma_u)$$

$$\frac{1}{n} \ln [P^a (P^b)^{-1}]$$

How to compare with data?

$$E[\chi_k(x^q)] = \frac{1}{2} \left[m_k - \ln (S_k^{-\frac{1}{2}} H_k P^a H_k^T S_k^{-\frac{1}{2}}) \right]$$

$2 E[\chi_k(x^q)]$ must be less than m_k

ECMWF operations ($\rho = 1.4 \times 10^6$)

$$\frac{2J_0}{\rho} = 0.38$$

Relative informative content of observations

as a whole ($n = 8 \times 10^6$)

$$\frac{\rho}{n} \left[1 - \frac{2J_0}{\rho} \right] = \frac{1.4 \times 10^6}{8 \times 10^6} [1 - 0.38] \approx 0.11$$

But system globally inconsistent anyway

Assimilation without satellite observations
(globally consistent)

$\frac{2J_0}{P}$ can be larger than 1

$$\frac{2J_0}{P} \approx 0.95$$

Relative informative content

$$\frac{P}{N} \left[1 - \frac{2J_0}{P} \right] = \frac{2.5 \times 10^5}{8 \times 10^6} [1 - 0.95] \approx 1.5 \times 10^{-3}$$

Seems very small. Observations more accurate than they are ~~or~~ supposed to be (and background ~~more~~ ^{less} accurate)?

Additional work is necessary.

13

$$x^a = \alpha y + (1-\alpha)x^b$$

$$x^a - y = (\alpha - 1)y + (1-\alpha)x^b$$

$$E[(x^a - y)^2] = (\alpha - 1)^2 \underbrace{[\sigma_y^2 + \sigma_b^2]}$$

correctly estimated (innovations)

$(\alpha - 1)^2$ too large

α too small

Observations are more accurate than they are supposed to be (and background is less accurate)

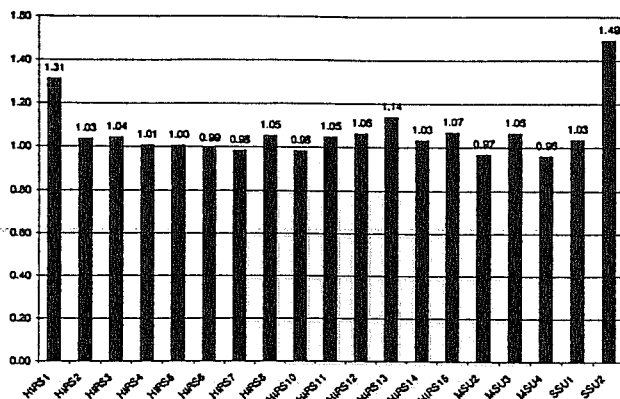


Figure 8. Tuning coefficients for NOAA14 channels after 10 iterations, *Simulated observations.*

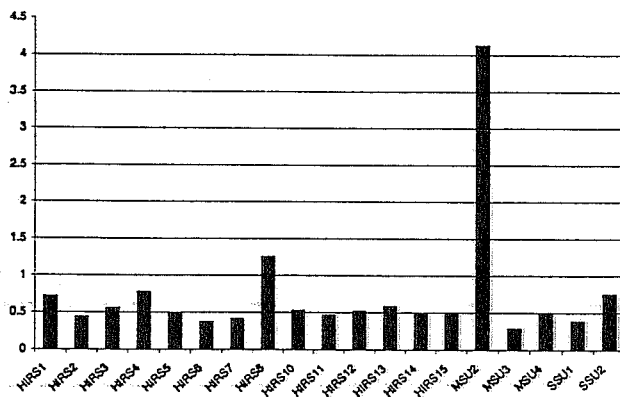


Figure 9. Tuning coefficients for NOAA14 channels after 5 iterations, *real data*

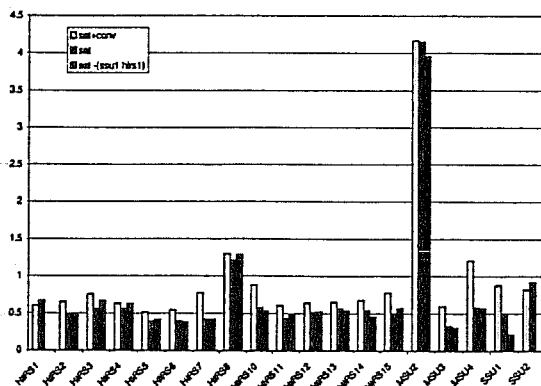


Figure 10. Tuning coefficients for NOAA14 channels computed: - 1 (white) with all other conventional observations analyzed, but not tuned. -2 (black) with NOAA14 channels only -3 (grey) with HIRS1 and SSU2 radiances removed.

Chapnik, 2003

Conclusions

- Only objective source of information on errors affecting the data is innovation vector $d = y - Hx^b$
- One-to-one transform between d and Data-mining-Analysis difference S . It is exactly equivalent to perform diagnostics on either one of those two vectors
- Any inconsistency between a priori assumed and a posteriori observed statistics can always be mathematically explained out without change to either the analysis or the estimated analysis error. Independent ^{hypotheses} ~~observations~~ which cannot be objectively validated (at least not on the basis of the innovation vector) will always be necessary.
- Once such hypotheses are made, adaptive adjustment of parameters becomes possible

- It is possible to quantify the relative contribution of any subset ~~to~~ of data to the overall accuracy of the assimilation

This particular diagnostic can be used, among others, for tuning the analysis parameters.

- Do systematically this kind of diagnostics on assimilation system, even (especially?) at early stages of development

- Extension to non linear Bayesian estimation?